

About One Method of Classification of a Wide Set of Trajectories

Ilia N. Tavkheldze

Tbilisi State University,

University str. 2, Tbilisi 0143, Georgia, E-mail: ilia.tavkheldze@tsu.ge

In this report is considered wide set of “**Complicated-Displacements**” which are presented by following analytic representation

$$X(\tau, \psi, \theta, t) = T_1(t) + \cos(\theta + M(t)) \times \\ [R(\theta, t) + p(\tau, \psi, \theta, t) \cos(n(\theta) + g(t)) - q(\tau, \psi, \theta, t) \sin(n(\theta) + g(t))]$$

$$Y(\tau, \psi, \theta, t) = T_2(t) + \sin(\theta + M(t)) \times \\ [R(\theta, t) + p(\tau, \psi, \theta, t) \cos(n(\theta) + g(t)) - q(\tau, \psi, \theta, t) \sin(n(\theta) + g(t))]$$

$$Z(\tau, \psi, \theta, t) = T_3(t) + K(\theta, t) + \\ p(\tau, \psi, \theta, t) \sin(n(\theta) + g(t)) + q(\tau, \psi, \theta, t) \cos(n(\theta) + g(t))$$

where X, Y, Z – Descartes coordinates; τ, ψ, θ - local coordinates; t – time arguments; T_i ($i=1,2,3$), M, R, K, p, q, g, n – are some “arbitrary” functions – “**Elementary Permutations**”;

We try to explain “responsibility” of each elementary permutation and frames of theirs “arbitrariness”. On the other hand we make analysis of two concrete mathematical models of complicated – displacement and theirs separation to the elementary permutations.